Foundations of Machine Learning Al2000 and Al5000

FoML-36 Tree-based methods

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So far in FoML

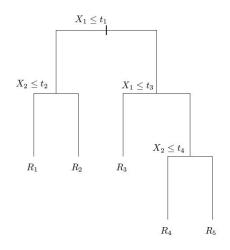
- Intro to ML and Probability refresher
- MLE, MAP, and fully Bayesian treatment
- Supervised learning
 - a. Linear Regression with basis functions
 - b. Bias-Variance Decomposition
 - c. Decision Theory three broad classification strategies
 - d. Neural Networks
- Unsupervised learning
 - a. K-Means, Hierarchical, and GMM for clustering
- Kernelizing linear Models
 - a. Dual representation, Kernel trick, SVM (max-margin classifier)





For today

Tree Based Learning Methods



Contents are taken from - Intro to Statistical Learning





Agenda

- Tree-based methods for
 - Regression
 - Classification
- Improvements
 - Bagging
 - Random Forests
 - Boosting





Involve stratifying or segmenting the input (predictor) space

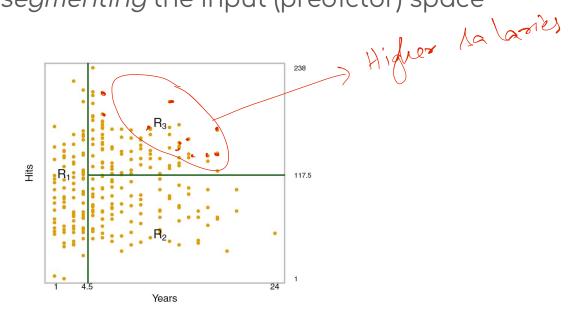




Figure credits: James et al. (ISLR)



 Prediction ← mean/mode of the training observations in that region



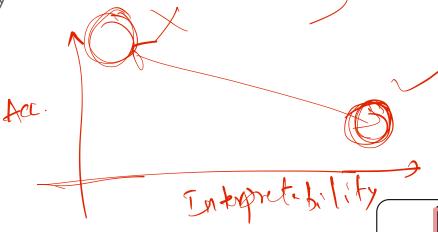


Splitting rules used for segmenting can be summarized in a tree →
 Decision Trees





- Simple and useful to interpret
- Typically not the best in the business
 - o Can be improved (e.g. bagging, random forests, boosting etc.)
 - At the cost of interpretability



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Decision Trees for Regression



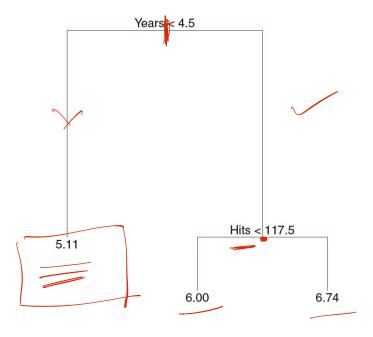


Example Problem

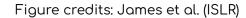
- Predicting the baseball players' (log) salary
- Based on the prior experience (years) and hits (in the past year)

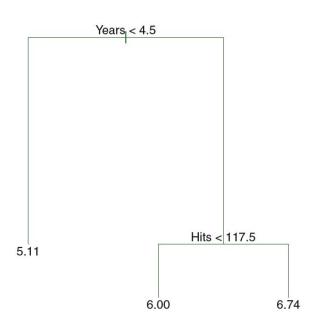








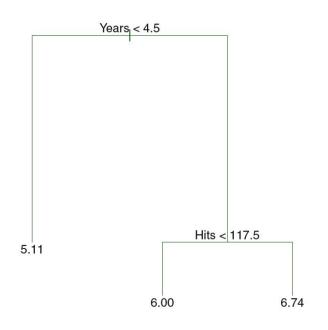




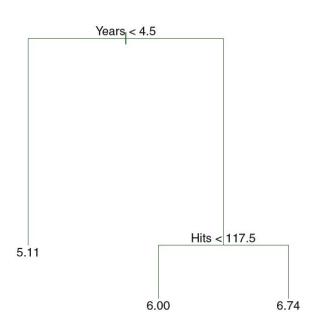
Top split

- Based on the experience (less than
 4.5 years → R₁)
- Avg. salary for that split is the mean of the training samples in that region
- \circ 5.107 → e^{5.107} thousands of USD





- Players above 4.5 years of experience
 → right split
- Further, split based on the hits in the previous year major league
- Less than 117.5 into second region (R_2), more than that into third region (R_3)

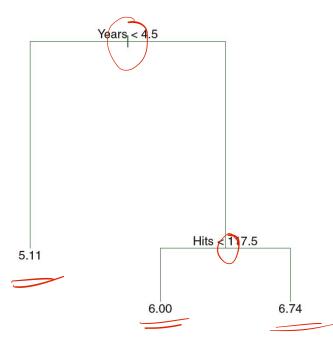


$$R_1 = \{X \mid Years < 4.5\}$$
 $R_2 = \{X \mid Years > = 4.5, Hits < 117.5\}$
 $R_3 = \{X \mid Years > = 4.5, Hits > = 117.5\}$



Figure credits: James et al. (ISLR)





$$R_1 = \{X \mid Years < 4.5\}$$

$$R_2 = \{X \mid Years > = 4.5, Hits < 117.5\}$$

$$R_3 = \{X \mid Years >= 4.5, Hits >= 117.5\}$$

Called the 'terminal' nodes or the 'leaves' of the tree. Others where the predictor space is split is called 'internal' nodes.

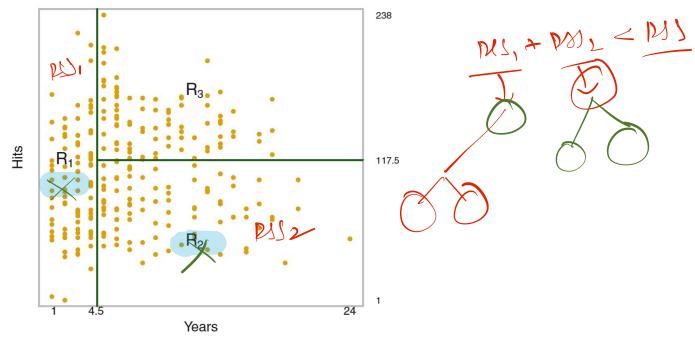


Figure credits: James et al. (ISLR)



The partitions in the predictor space







Interpreting the Tree

- data Criente Model
- 1. Experience is the most important factor that determines the salary
 - Players with less experience earn less
- 2. Given that a player is less experienced, the number of hits he made in the last year play little role in the salary
- 3. For the experienced players, number of hits made recently affect their salary. More hits → more salary



Interpreting the Tree

- Probably an over-simplification of the true relation b/w {Year, Hits}
 and Salary
- However the advantage is that it is easier to interpret and has a nice graphical representation





Stratification of the Feature Space



Building a Regression Tree

1. Divide the predictor space (i.e set of possible values for X_1 , X_2 , ... X_p) into J distinct and non-overlapping regions (R_1 , R_2 ,.... R_p)



Stratification of the Feature Space

Building a Regression Tree

2. For every R_j , make the same prediction which is the mean of the response value for training samples in R_i





• Could have any shape. But for simplicity we choose high-dim rectangles







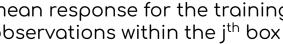
- Could have any shape. But for simplicity we choose high-dim rectangles
- The goal is to find boxes R₁, R₂, R₁ that minimizes the RSS

$$\sum_{j=1}^{J} \sum_{i \in R_j} (y_i - \hat{y}_{R_j})^2$$

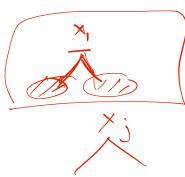
 \times : = $\left\{0, 1, .2\right\}$



mean response for the training observations within the jth box



- Infeasible to consider every possible partition
- Instead take a top-down, greedy approach → recursive binary splitting







- Top-down: starts at the top of the tree and recursively splits the predictor space
- Greedy: at each step, best split is made at that particular step
 - o rather than looking ahead and picking a split that will lead to a better tree later





Recursive Binary Splitting

 First select the predictor X_j, and then the cutpoint s → leads to a greatest reduction in RSS





Recursive Binary Splitting

$$R_1(j,s) = \{X | X_j < s\} \text{ and } R_2(j,s) = \{X | X_j \ge s\}$$

seek the value of j and s that minimize the equation

$$\sum_{i: x_i \in R_1(j,s)} (y_i - \hat{y}_{R_1})^2 + \sum_{i: x_i \in R_2(j,s)} (y_i - \hat{y}_{R_2})^2$$





Recursive Binary Splitting

- Next we repeat the process: look for the best predictor and best cutpoint that minimizes the RSS further
- But this time we split one of the two previously identified regions





Recursive Binary Splitting

- Continue until a stopping criterion is reached
 - E.g., until no region contains more than five observations





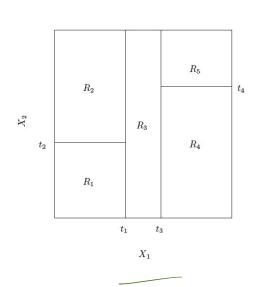
Recursive Binary Splitting

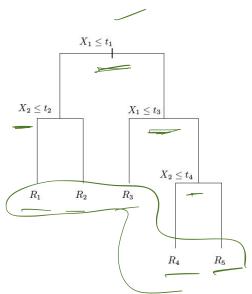
 Once the regions are identified, prediction is the mean response of the training samples in that region





Recursive Binary Splitting (a 5 region example)





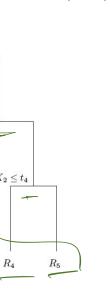




Figure credits: James et al. (ISLR)

Overfitting

- Above procedure may give good predictions on training data
 - But likely to overfit
- This is because the resulting tree may be too complex





Overfitting

- Smaller tree with fewer splits might lead to lesser variance and better interpretation
 - At the cost of a little bias





Overfitting

- One way to achieve this
 - o build the tree only when the decrease in the RSS due to each split exceeds some (high) threshold
 - Results in smaller trees, but is short-sighted





Tree Pruning

- Grow a large tree, then prune it back to obtain a subtree
- How to find the best subtree?
 - o Intuitively, pick the one with min. test/validation error





Tree Pruning

• Estimating the cross-validation error for every possible subtree is cumbersome (large number of subtrees are possible)

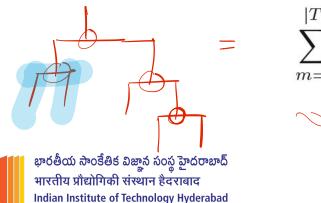




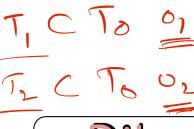
Tree Pruning - Cost Complexity Pruning

- Also known as weakest link pruning
- Rather than considering every possible subtree, consider a sequence of subtrees indexed by α
- For each value of α , \exists a subtree $T \subset T_0$ s.t. the equation is = 0.

 minimum $\alpha = 10$



$$\sum_{m=1}^{|T|} \sum_{i: x_i \in R_m} (y_i - \hat{y}_{R_m})^2 + \alpha |T|$$





Tree Pruning - Cost Complexity Pruning

- As we increase α , branches get pruned in a nested fashion
- We can select the value of α from cross-validation

$$\sum_{m=1}^{|T|} \sum_{i: x_i \in R_m} (y_i - \hat{y}_{R_m})^2 + \alpha |T|$$





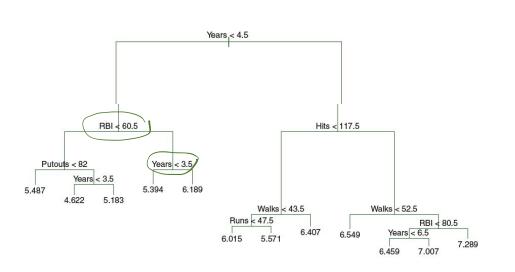
Tree Pruning - Cost Complexity Pruning

- 1. Grow large tree using recursive binary splitting
- Apply cost complexity pruning \rightarrow obtain a sequence of subtrees as a function of α
 - 3. Compute the validation (or cross validation) performance and pick the best α that minimizes the error
- 4. Return the subtree from step 2 that corresponds to the chosen q





Baseball Salaries Example



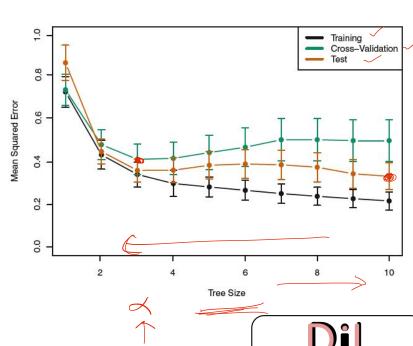




Figure credits: James et al. (ISLR)



Classification Trees





Trees for Classification

- Similar to the Regression Trees
- Except, predict a qualitative response



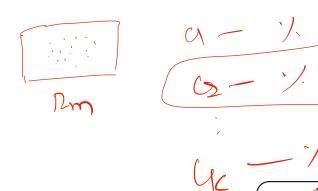


Prediction in Classification Trees

 The most commonly occurring class of training observations in the region - Majority voting

Mean for Regression

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Prediction in Classification Trees

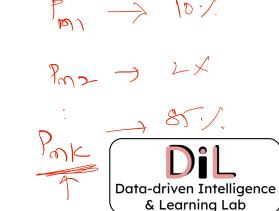
- Along with the class prediction for a terminal node
 - o class proportions within the regions of terminal nodes





- Recursive binary splitting
- RSS will not do, a natural alternative is classification error
 - Fraction of the training observations in that region (R_m) that do not belong to the most common class

$$E = 1 - \max_{k} (\hat{p}_{mk})$$





- Classification error is not very sensitive for tree-growing
 - Two more metrics
- Gini Index and Entropy





- Gini Index → minimizes the total variance across the K classes
 - Referred to as a measure of node purity
 - Small value → node contains predominantly observations from a single class

$$G = \sum_{k=1}^{K} \hat{p}_{mk} (1 - \hat{p}_{mk})$$





- Entropy
 - Also serves as a measure of node purity
 - Small value → node contains predominantly observations from a single class

$$D = -\sum_{k=1}^{K} \hat{p}_{mk} \log \hat{p}_{mk}$$





Pruning a Classification Tree

- Any of the three metrics can be used
 - o classification error might be preferred if prediction accuracy is the goal



Heart Disease Example

- Binary outcome (Yes or No)
- 13 predictors: Age, Sex, Chol, heart and lung function measurements etc.



Heart Disease Example

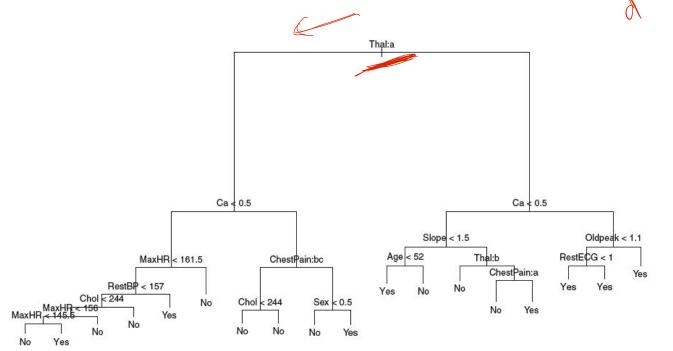




Figure credits: James et al. (ISLR)



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Heart Disease Example

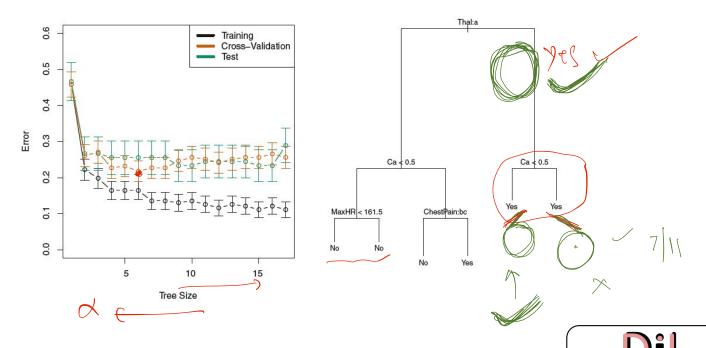




Figure credits: James et al. (ISLR)

Some Notes

- Trees can be constructed in the presence of qualitative variable
 - E.g. Sex and Thal variables
- Some of the splits yield two terminal nodes that have the same predicted value
 - RestECG < 1
 - Why? → leads to increased node purity (all 9 of right split observations has a response of yes, whereas 7/11 of left split observations have Yes response)





Trees vs. Linear Models





Trees vs. Linear Regression

$$f(X) = \sum_{m=1}^{M} c_m \cdot 1_{(X \in R_m)}$$

$$f(X) = \beta_0 + \sum_{j=1}^p X_j \beta_j$$



Trees vs. Linear Regression

- Which model is better?
 - o Depends on the problem at hand
- If the relationship between the features and response is well approximated by the linear model
 - LR is likely to work better (RT does not exploit the linear structure)
- If there is a highly nonlinear and complex relationship
 - o Decision Trees may outperform the classical methods





Trees vs. Linear Regression

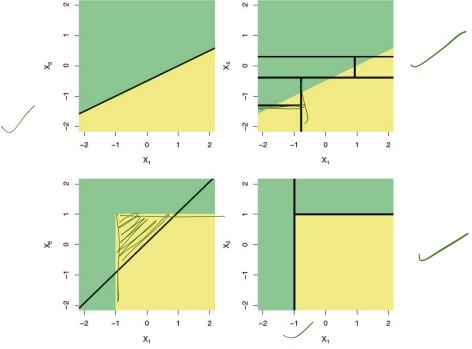




Figure credits: James et al. (ISLR)



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Advantages of Trees

- Very easy to explain to people
 - Some believe that they mirror human decision-making
- Can be displayed graphically (even to a non-expert)
- Can handle qualitative variables
 - Without the necessity of dummy variable





Disadvantages of Trees

- Generally do not have the same level of predictive accuracy than some of the other techniques
- Can be non-robust
 - o Small change in data may cause a large change in the final estimated tree



Next: More powerful prediction models

- Model combination tools
 - Bagging and Boosting





Thank You



