

# Foundations of Machine Learning

## AI2000 and AI5000

FoML-10

Bias Variance Decomposition

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# So far in FoML

- What is ML and the learning paradigms
- Probability refresher
- MLE, MAP, and fully Bayesian treatment
- Linear Regression with basis functions - and regularization
- Model selection



# Breaking down the prediction error of a model

# Frequentist interpretation of the model complexity



# Expected Loss for Regression

- Regression loss  $L(t, y(\mathbf{x})) = [t - y(\mathbf{x})]^2$   
for a given  $(\mathbf{x}, t) \sim P(\mathbf{x}, t)$



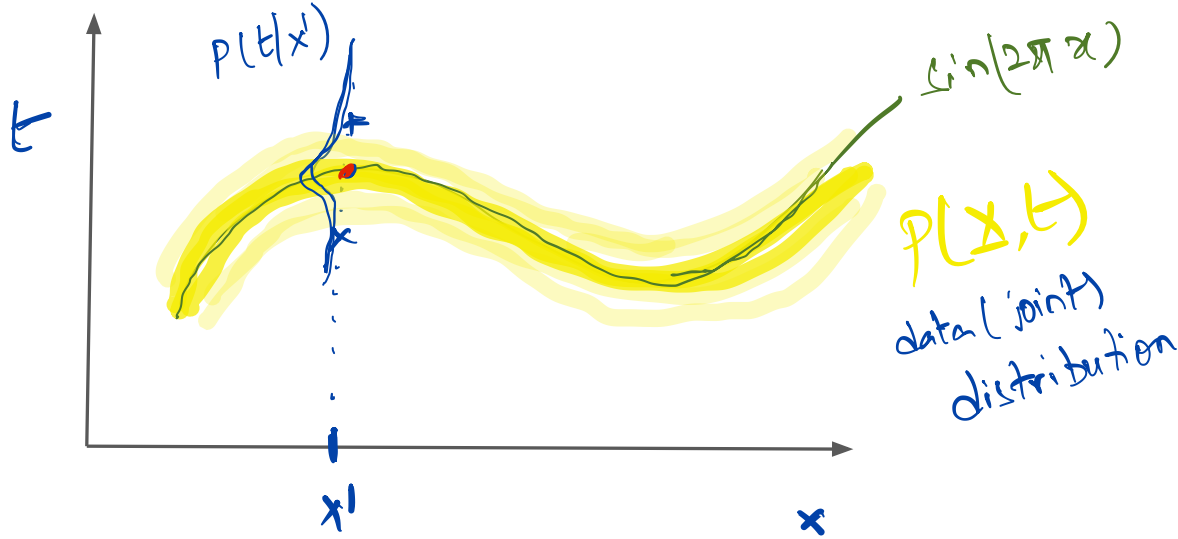
# Expected Loss for Regression

- Regression loss  $L(t, y(\mathbf{x})) = [t - y(\mathbf{x})]^2$   
for a given  $(\mathbf{x}, t) \sim P(\mathbf{x}, t)$

- If we know the data distribution, we can find the

$$\mathbb{E}[L(t, y(\mathbf{x}))] = \iint [t - y(\mathbf{x})]^2 P(\mathbf{x}, t) d\mathbf{x} dt$$

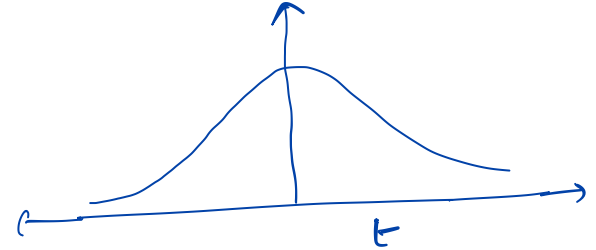
# Data and prediction distributions



$$t = \sin 2\pi x + \epsilon$$

$$\epsilon \sim \mathcal{N}(0, \bar{\sigma}^2)$$

$$p(t|x)$$



# Minimizing the Expected loss at given $x$

$$L = \int [t - y(x)]^2 p(t|x) dt$$
$$\frac{\partial L}{\partial y(x)} = 2 \int [t - y(x)] p(t|x) dt = 0$$

$$\int t p(t|x) dt = \int y(x) p(t|x) dt$$

$$E[t|x] = y(x)$$

Regression function



# Expected Loss for Regression

$$\mathbb{E}[L] = \int \int (y(\mathbf{x}) - t)^2 p(\mathbf{x}, t) dt d\mathbf{x}$$

$$= \mathbb{E}_{\mathbf{x}, t} [(y(\mathbf{x}) - t)^2] = \mathbb{E}_{\mathbf{x}, t} [(y(\mathbf{x}) - \mathbb{E}[y_{\mathbf{x}}] + \mathbb{E}[y_{\mathbf{x}}] - t)^2]$$

$$= \underbrace{\mathbb{E}_{\mathbf{x}, t} [(y(\mathbf{x}) - \mathbb{E}[y_{\mathbf{x}}])^2]}_{\text{Due to the model}} + \underbrace{\mathbb{E}_{\mathbf{x}, t} [(\mathbb{E}[y_{\mathbf{x}}] - t)^2]}_{\text{Due to the intrinsic noise}}$$

cross terms  
vanish

$$\mathbb{E}_{\mathbf{x}, t} [(y(\mathbf{x}) - \mathbb{E}[y_{\mathbf{x}}]) \cdot (\mathbb{E}[y_{\mathbf{x}}] - t)]$$

$$= \mathbb{E}_{\mathbf{x}} [\underbrace{\mathbb{E}_t [(y(\mathbf{x}) - \mathbb{E}[y_{\mathbf{x}}]) \cdot (\mathbb{E}[y_{\mathbf{x}}] - t) | \mathbf{x}]}_0]$$



# Minimizing the expected loss

$$\mathbb{E}[L] = \int \{y(\mathbf{x}) - \mathbb{E}[t/\mathbf{x}]\}^2 p(\mathbf{x}) d\mathbf{x} + \int \text{var}[t/\mathbf{x}] p(\mathbf{x}) d\mathbf{x}$$

- Optimal solution is unknown  $y(\mathbf{x}) = \mathbb{E}[t/\mathbf{x}]$

if we model  $\mathbb{E}[t/\mathbf{x}]$  using parameters  $\underline{\omega}$ , then from a Bayesian perspective we can express the model's uncertainty via a posterior on  $\underline{\omega}$

But we make point estimate for  $\underline{\omega}$  on a dataset  $D$



# Minimizing the expected loss

$$\mathbb{E}[L] = \int \underbrace{\{y(\mathbf{x}) - \mathbb{E}[t/\mathbf{x}]\}^2}_{\text{Optimal solution is unknown}} p(\mathbf{x}) d\mathbf{x} + \int \underbrace{\text{var}[t/\mathbf{x}]}_{y(\mathbf{x}) = \mathbb{E}[t/\mathbf{x}]} p(\mathbf{x}) d\mathbf{x}$$

- Optimal solution is unknown  $y(\mathbf{x}) = \mathbb{E}[t/\mathbf{x}]$
- We only have finite dataset (but not the distribution)

$$D = \{(x_1, t_1), \dots, (x_n, t_n)\}$$



# Minimizing the expected loss

$$\mathbb{E}[L] = \int \{y(\mathbf{x}) - \mathbb{E}[t/\mathbf{x}]\}^2 p(\mathbf{x}) d\mathbf{x} + \int \text{var}[t/\mathbf{x}] p(\mathbf{x}) d\mathbf{x}$$

- Frequentist approach → multiple datasets, multiple models

$$D_1 = \{ \dots \} \quad D_2 = \{ \dots \} \quad \dots \quad D_L = \{ \dots \}$$

$y_1$        $y_2$        $y_L$

$$\mathbb{E}_D[(y_D(\mathbf{x}) - \mathbb{E}[t/\mathbf{x}])^2]$$

Estimate the performance by averaging  
the expected loss over different  
datasets



# Minimizing the expected loss

$$\mathbb{E}[\mathbb{E}_D[L]] = \int \mathbb{E}_D[(y_D(\mathbf{x}) - \mathbb{E}[t/\mathbf{x}])^2]p(\mathbf{x})d\mathbf{x} + \int \text{var}[t/\mathbf{x}]p(\mathbf{x})d\mathbf{x}$$

- Bias-Variance decomposition



# Minimizing the expected loss

$$\mathbb{E}[\mathbb{E}_D[L]] = \int \mathbb{E}_D[(y_D(\mathbf{x}) - \mathbb{E}[t/\mathbf{x}])^2] p(\mathbf{x}) d\mathbf{x} + \int \text{var}[t/\mathbf{x}] p(\mathbf{x}) d\mathbf{x}$$

- Bias-Variance decomposition

$$\mathbb{E}_D[(y_D(\mathbf{x}) - \mathbb{E}[t/\mathbf{x}])^2] = \mathbb{E}_D[(y_D(\mathbf{x}) - \mathbb{E}_D[y_D(\mathbf{x})] + \mathbb{E}_D[y_D(\mathbf{x})] - \mathbb{E}[t/\mathbf{x}])^2]$$

$$(\text{Bias})^2 = \int \mathbb{E}_D[\{y_D(\mathbf{x}) - \mathbb{E}[t/\mathbf{x}]\}^2] p(\mathbf{x}) d\mathbf{x} \quad \underbrace{\mathbb{E}_D[\{y_D(\mathbf{x}) - \mathbb{E}_D[y_D(\mathbf{x})]\}^2]}_{\text{variance}} + \underbrace{\mathbb{E}_D[\{\mathbb{E}_D[y_D(\mathbf{x})] - \mathbb{E}[t/\mathbf{x}]\}^2]}_{\text{Bias}^2}$$

$$\text{Variance} = \int \mathbb{E}_D[\{y_D(\mathbf{x}) - \mathbb{E}_D[y_D(\mathbf{x})]\}^2] p(\mathbf{x}) d\mathbf{x}$$

$$\text{Noise} = \int \text{var}[t/\mathbf{x}] p(\mathbf{x}) d\mathbf{x}$$



# Example



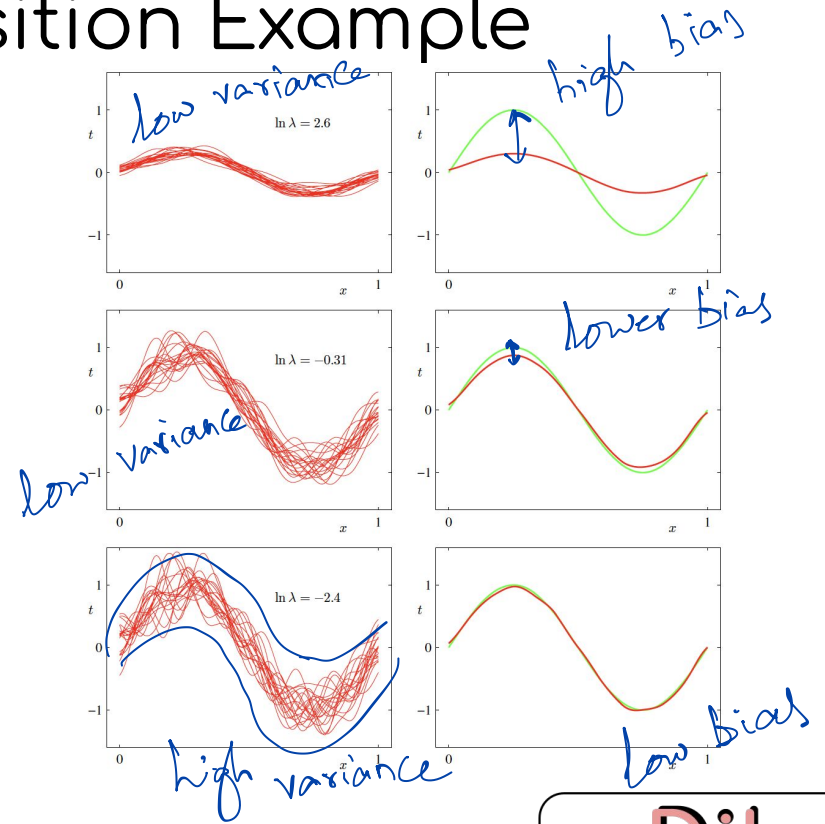
# Bias-Variance Decomposition Example

- 100 datasets of size 25
- $x \sim U[0, 1]$
- $t = \sin(2\pi x) + \epsilon$

$$y^{(d)} = \omega^{(d)T} \phi(x)$$

$d = 1 \text{ to } 100$

$$\mathbb{E}_D[y_D(x)] = \bar{y}(x)$$



# Bias-Variance Decomposition Example

(quantifying)

Estimating the bias and variance [since we know the ground truth]

$$(\text{bias})^2 = \int \{\mathbb{E}_D[y_D(x) - \mathbb{E}[t/x]]^2 p(x) dx =$$

$$\frac{1}{N} \sum_{i=1}^N \left\{ \bar{y}(x_i) - \mathbb{E}(t/x_i) \right\}^2$$

Numerical integration over  $\{x_1, x_2, \dots, x_N\}$  Monte Carlo approximation

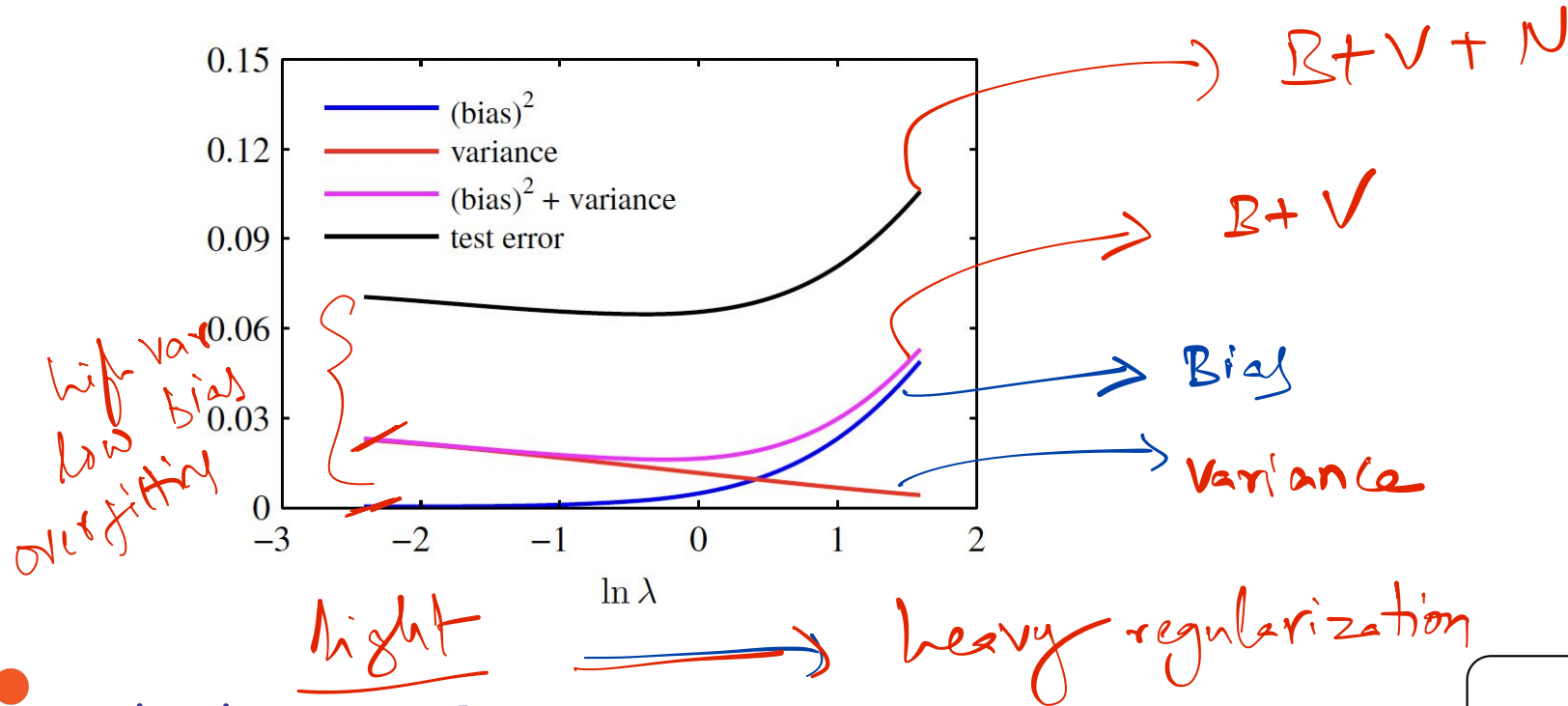
$$\text{variance} = \mathbb{E}_D[\{y_D(x) - \mathbb{E}_D[y_D(x)]\}^2 p(x) dx$$

$$= \frac{1}{N} \sum_{i=1}^N \frac{1}{L} \sum_{l=1}^L \left[ y^{(l)}(x_i) - \bar{y}(x_i) \right]^2$$

$$\begin{aligned} \bar{y}(x) &= \mathbb{E}_D[y_D(x)] \\ &= \frac{1}{L} \sum_{l=1}^L y^{(l)}(x) \end{aligned}$$



# Bias-Variance Decomposition Example



# Bias-Variance Decomposition

- In practice - we don't split our dataset to determine the model complexity
  - Large datasets are better
- Bayesian regression!

# Rough work



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# Next Bayesian Regression

