Foundations of Machine Learning Al2000 and Al5000

FoML-03 Probability - Expectation, Variance and Gaussian Distribution

Dr. Konda Reddy Mopuri
Department of AI, IIT Hyderabad
July-Nov 2025





So far in FoML

- What is ML and the learning paradigms
- Probability refresher
 - Sum rule, product rule, Random variables, Bayes Theorem, Independence





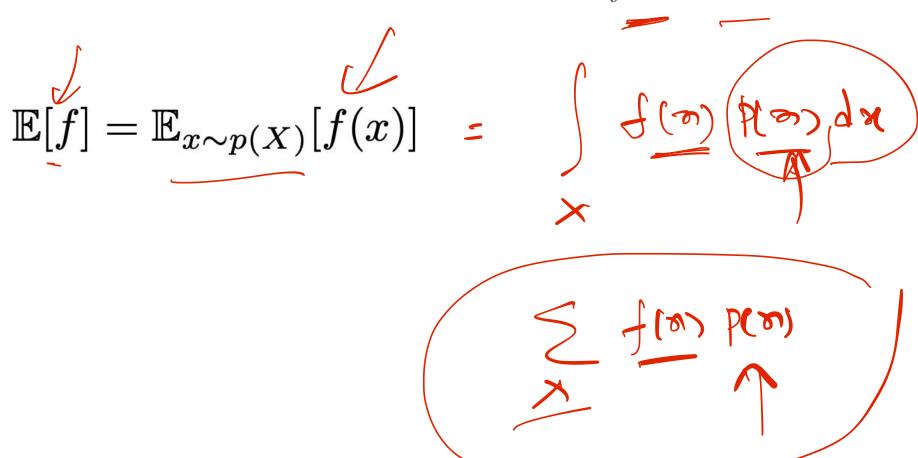
Expectation, Variance and the Gaussian Distribution





Expectation

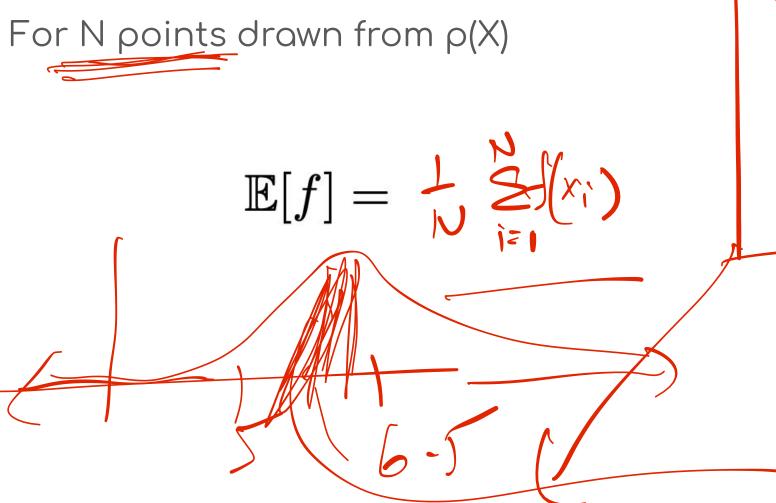
• Random variable X and a function $f: X \to \mathbb{R}$

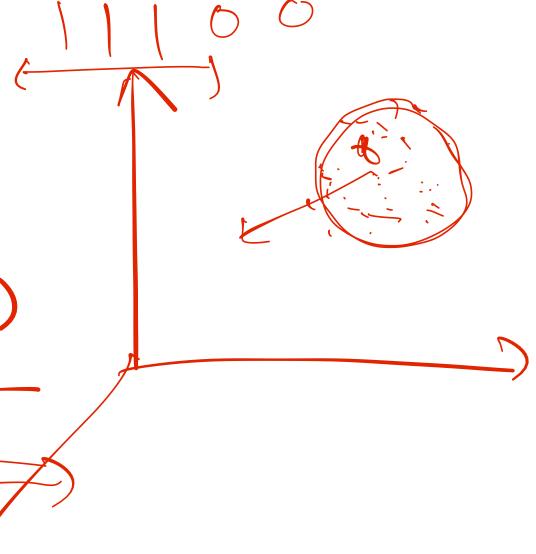






Expectation







Data-driven Intelligence & Learning Lab

Expectation

Conditional expectation

$$\mathbb{E}[f/y] = \mathbb{E}_{x \sim p(X/Y=y)}[f(x)] = \underbrace{\begin{cases} \leq \\ \end{cases}} \underbrace{f(x)} \underbrace$$

$$\int f(\alpha x + \beta y) = \alpha f(x) + \beta f(y)$$



Data-driven Intelligence & Learning Lab

Variance

ullet Expected quadratic distance between f and its mean ${\mathbb E}[f]$

$$var(f) = \mathbb{E}(f(n) - \mathbb{E}(f(n)))$$

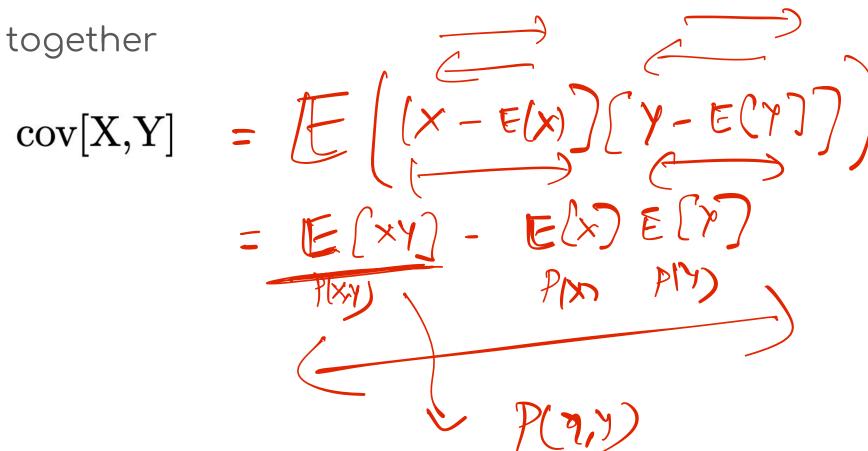
$$= \mathbb{E}(f(n)) - \mathbb{E}(f(n))$$

$$= \mathbb{E}(f(n)) - \mathbb{E}(f(n))$$



Covariance

Measures the extent to which two random variables X and Y vary







Covariance



- X and Y are vectors of random variables
- Covariance matrix

$$cov[X,Y] = \begin{bmatrix} x - E(x) \\ y - E(x) \end{bmatrix}$$



Covariance

Between independent variables

$$cov[X,Y] = \mathbb{E}[Y] - \mathbb{E}[Y]$$

$$= \mathbb{E}[X] \mathbb{E}[Y]$$

$$= 0$$



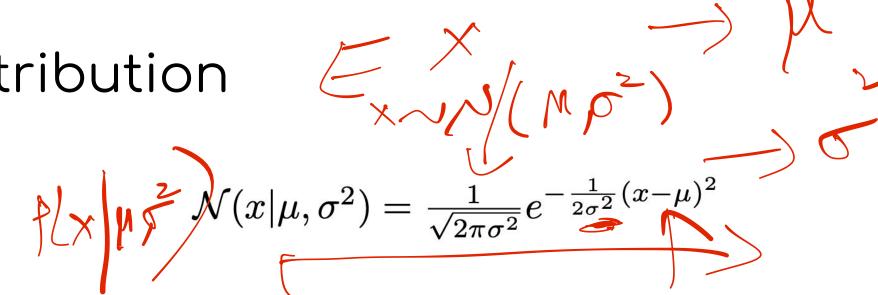


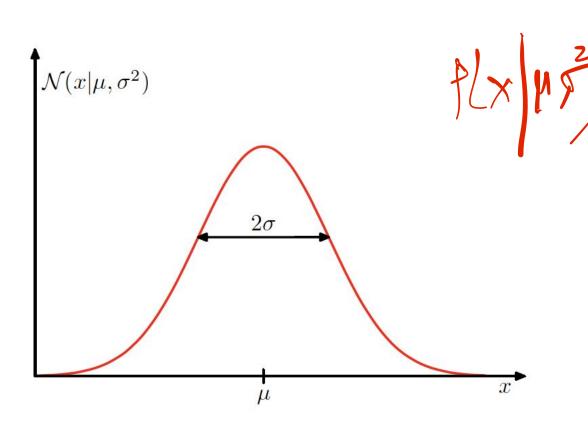
Gaussian Distribution





Gaussian Distribution





$$x \sim \mathcal{N}(x|\mu, \sigma^2)$$

$$\mathbb{E}[x] = \mu \qquad \text{Var}(x) = \sigma^2$$

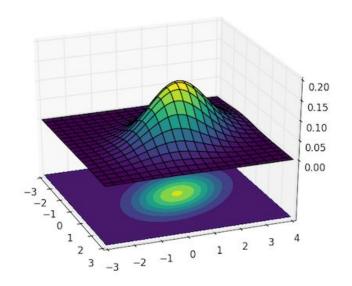




Multivariate Gaussian Distribution

ullet D-dimensional vector $\mathbf{x}=(x_1,x_2,\dots x_D)^T$

$$\mathcal{N}(\mathbf{x}|\mu, \Sigma) = \frac{1}{(2\pi)^{D/2} |\mathbf{\Sigma}|^{1/2}} \exp\left(-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^{\top} \mathbf{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu})\right)$$







Next Maximum Likelihood Principle



