

Deep Learning for Computer Vision

Dr. Konda Reddy Mopuri Mehta Family School of Data Science and Artificial Intelligence IIT Guwahati Aug-Dec 2022



• Computer Vision: What and Why?



- Computer Vision: What and Why?
- Brief history of Computer Vision



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- This Course: structure, organization



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- Brief history of Computer Vision
- This Course: structure, organization
- Logistics and Resources





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 - Extract meaningful information from the visual world via digital images and videos



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 - Extract meaningful information from the visual world via digital images and videos
 - And, recommend appropriate actions based on that
- Simply, enabling machines to see as humans do!









• How many sticky notes are there?

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- How many sticky notes are there?
- What is the object that is new in the scene?

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- How many sticky notes are there?
- What is the object that is new in the scene?
- Is there something to eat/drink here?

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Images from the 'Objects out of the context' dataset





Images from the 'Objects out of the context' dataset

• What is wrong with each of these images?

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- How many sticky notes are there?
- What is the object that is new in the scene?
- What is wrong with each of these images?

Computer Vision

Can we make machines answer these questions?



More formally

Building artificial systems that can process, perceive, and reason about the visual world (Taken from Justin Johnson, U.Mich.)



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Building artificial systems that can process, perceive, and reason about the visual world (Taken from Justin Johnson, U.Mich.)

Other definitions

- "construction of explicit, meaningful descriptions of physical objects form images" (Ballard & Brown, 1982)
- "computing properties of the 3D world from one or more images" (Trucco & Verri, 1998)
- "to make useful decisions about real physical objects and scenes based on sensed images" (Sockman & Shapiro, 2001)

Why CV? Application Areas





Autonomy (Credits: Getty Images)



Healthcare (Credits:Nvidia.Developer)



Surveillance (Credits:Flickr)



Manufacturing (Credits: Moonvision)



HCI (Credits:X-tech.am)



Sports (Credits:Medium and Sasank Gurajapu)





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Al-Complete

- One of the most difficult problems in AI
- Would not be possible to solve with a simple specific algorithm



• Semantic gap



Source: Wikipedia

Computer Vision: Themes





Taken from Prof. Vineet N Subramanian, IITH

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Computer Vision: this course







Brief History: David Hubel and Torsten Wiesel (1959)

• Receptive fields of single neurons in the cat's striate cortex [Link to the experiment]



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 - Visual processing starts with simple structures such as oriented edges (Remember this!)



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- Established that simple and complex neurons exist in visual cortex
- Visual processing starts with simple structures such as oriented edges (Remember this!)
- Went on to win a Nobel in 1981!



Source

(1959)

Brief History: Russel kirsch (1959)



Source

• First digital image

Brief History: Russel kirsch (1959)



- First digital image
- 176×176 , 5cm in size

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- First digital image
 - 176×176 , 5cm in size
 - Preserved in the Portland Art Museum



Brief History: Lawrence Roberts (1963)



• Machine perception of three-dimensional solids



Camera Transformation

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- Thesis described the process of deriving 3D info about solid objects from their 2D images of line drawings



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- Camera transformations, perspective effects, depth perception, etc.



Camera Transformation

Brief History: Summer vision project (1966

• Seymour Papert and Gerald Sussman (Aim document)

Goals - General

The primary goal of the project is to construct a system of programs which will divide a vidisector picture into regions such as likely objects likely background areas

chaos.

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- Intended to develop a system for FG/BG segmentation, extracting non-overlapping objects from the real-world images

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- Intended to develop a system for FG/BG segmentation, extracting non-overlapping objects from the real-world images
- 60 years later, the world is still working on it!

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- MIT's AI lab offered first Machine Vision course
- First CV product for OCR (by Raymond Kurzweil)
- Object recognition through shape analysis (Generalized Cylinders, Skeletons, etc.)

Brief History: David Marr (1982)



• "Vision: A computational investigation into the human representation and processing of visual information"

Brief History: David Marr (1982)



- "Vision: A computational investigation into the human representation and processing of visual information"
- Established the "Hierarchy" of the vision: high-level understanding of visual data is built on top of the low-level tools for detecting edges, curves, corners, etc.

David Marr's Representational framework (1982)



• Primal sketch of the image (edges, boundaries, etc.) are represented

Rostyslav Demush, medium.com

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David Marr's Representational framework (1982)



- Primal sketch of the image (edges, boundaries, etc.) are represented
- 2.5D representation: depth and discontinuities are represented
- 3D model hierarchically organized in terms of surface and volumetric primitives

Rostyslav Demush, medium.com

Brief History: Neocognitron (1979-82)



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- Used for hand-written digit recognition
- Viewed as precursor for the modern CNNs (had conv filters and layers, spatial invariance)



Brief History: Optical Flow (1981)



• Determining Optical Flow by Horn and Schunck



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- Determining Optical Flow by Horn and Schunck
- Estimates the direction and speed of moving objects across pair of images



Brief History: Canny Edge detection (1986)

 Multi-stage approach for detecting the edge content in an image



Source:OpenCV

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- Signal variations are dealt with calculus (simple but popular method)



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Brief History: Canny Edge detection (1986)

- Multi-stage approach for detecting the edge content in an image
- Signal variations are dealt with calculus (simple but popular method)
- Developed as a masters student, published in Trans. on PAMI, 1986 (Link)



Source:OpenCV

Brief History: Recognition by components (1987)



 Bottom-up process for object recognition proposed by Irving Biederman



Source: Prof. Kenneth M. Steele

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- Bottom-up process for object recognition proposed by Irving Biederman
- Simple 3D shapes (geons) such as cones and cylinders compose objects



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Brief History: snakes and Contours (1988)



• Active contour models (Snakes) aim to outline the objects of interest from the images



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- Active contour models (Snakes) aim to outline the objects of interest from the images
- Widely applied in edge detection, segmentation, shape recognition, object tracking, etc.



Brief History: Backpropagation (1989)

Additive of Technologi

 Prof. Yan Lecun applied a backprop style learning algorithm to Fukushima's convolutional neural network



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- Very similar to modern CNN architectures
- Backpropagation is attributed 'Majorly' to Paul Werbos 1974 (although it was independently discovered by multiple from 1960s)







• Image Pyramids and scale-space processing



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- Wavelets



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- Wavelets
- Markov Random Fields



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- Variational Optimization Methods



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- Deformable parts model (Felzenszwalb et al, 2009)



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- Scene-graphs; (2017)
- Higher-levels of abstraction: VCR dataset, panoptic segmentation, etc. (2018-19)



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Turing Award winners for 2018

More history: to be written!



WE HAVE A LONG Way to go and a Lot of work to Do.

QUOTEHD.COM

Zach Hall

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Course Contents



- Part-1: Foundations of Deep learning (Implementing and training different types of neural networks)
 - (MP, perceptron), MLP, CNNs, and RNNs (LSTM and GRU)
 - Gradient Descent technique using the Backpropagation
 - Implement them in PyTorch framework (this is not a lab course, so it is majorly your responsibility!)

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- Part-2: Applications in Computer Vision (with a slight research flavour)
 - Object recognition, detection, semantic segmentation Vision and Language
 - Generative models: GANs and VAEs
 - Recent trends

Prerequisites



Theory

- Knowledge on basics of probability, linear algebra, and calculus
- Basic course on ML
- Exposure to Deep learning (a course greatly helps)

Practicals

- Programming in Python
- Knowledge of a deep learning framework (we work with PyTorch)

Time slot



• D1 slot

- Monday 4 4:55 PM
- Tuesday 4 4:54 PM
- Friday 3 3:55 PM

Time slot



• Open elective (Final year B.Tech, M.Tech, and Ph.D.)

Time slot



- Open elective (Final year B.Tech, M.Tech, and Ph.D.)
- Class Room 4104 (CORE-4, First Floor)

Logistics



• Course website: https://krmopuri.github.io/dl4cv/

- Course updates
- Lecture slides and other material
- Assignments
- etc.

Evaluation (Tentative)



- Assignments 30%
- Mid-semester 20%
- $\bullet~$ End-semester 30%~ Mini-project 20%~

Textbooks and References



Computer Vision

- O Computer Vision: A Modern Approach, Forsyth and Ponce
- Ocomputer Vision: Algorithms and Applications, Richard Szeliski

Deep Learning

- O Deep Learning textbook by lan Goodfellow et al.
- NPTEL course by Prof. Mitesh Khapra, IITM.
- Michael Nielsen's text book on NN & DL
- OL course by François Fleuret, EPFL and Uni. of Geneva
- PyTorch https://pytorch.org/
- Many more that I could not list and am not aware of...

DL for CV

- NPTEL Course by Prof. Vineet Balasubramanian, IITH.
- O Course by Dr. Justin Johnson, University of Michigan