

Deep Learning

14 Encoder-Decoder Models & Attention

Dr. Konda Reddy Mopuri Dept. of Al, IIT Hyderabad Jan-May 2024



• I/p is a sequence: X_1, X_2, \ldots, X_N



- I/p is a sequence: X_1, X_2, \ldots, X_N
- O/p is a sequence: Y_1, Y_2, \ldots, Y_M



- I/p is a sequence: X_1, X_2, \ldots, X_N
- O/p is a sequence: Y_1, Y_2, \ldots, Y_M
 - ASR: Speech i/p \rightarrow word sequence



- I/p is a sequence: X_1, X_2, \ldots, X_N
- O/p is a sequence: Y_1, Y_2, \ldots, Y_M
 - $\bullet~\mbox{ASR:}$ Speech $i/p \rightarrow \mbox{word}$ sequence
 - Machine Translation: word sequence \rightarrow word sequence



- I/p is a sequence: X_1, X_2, \ldots, X_N
- O/p is a sequence: Y_1, Y_2, \ldots, Y_M
 - $\bullet~\mbox{ASR:}$ Speech $i/p \rightarrow \mbox{word}$ sequence
 - ${\scriptstyle \bullet}$ Machine Translation: word sequence ${\rightarrow}$ word sequence
 - Dialog: user statement \rightarrow system response



- I/p is a sequence: X_1, X_2, \ldots, X_N
- O/p is a sequence: Y_1, Y_2, \ldots, Y_M
 - $\bullet~\mbox{ASR:}$ Speech $i/p \rightarrow \mbox{word}$ sequence
 - ${\scriptstyle \bullet}$ Machine Translation: word sequence ${\rightarrow}$ word sequence
 - $\bullet\,$ Dialog: user statement $\rightarrow\,$ system response
 - ${\scriptstyle \bullet }$ Question Answering: Question $i/p \rightarrow$ Answer



• No synchrony between X and Y $(M \neq N)$



- No synchrony between X and Y $(M \neq N)$
- May not even maintain the order of the symbols



- No synchrony between X and Y $(M \neq N)$
- May not even maintain the order of the symbols
- O/p symbols may not seem related to i/p



- No synchrony between X and Y $(M \neq N)$
- May not even maintain the order of the symbols
- ${\ensuremath{\, \circ }}$ O/p symbols may not seem related to i/p
- E.g., The check I issued could not be encashed. \rightarrow Did you check the balance in your account?



Naturalism and decision for the majority of Arab countries' capitalide was grounded by the Irish language by [[John Clair]], [[An Imperial Japanese Revolt]], associated with Guangzham's sovereignty. His generals were the powerful ruler of the Portugal in the [[Protestant Immineners]], which could be said to be directly in Cantonese Communication, which followed a ceremony and set inspired prison, training. The emperor travelled back to [[Antioch, Perth, October 25/21]] to note, the Kingdom of Costa Rica, unsuccessful fashioned the [[Thrales]], [[Cynth's Dajoard]], known in western [[Scotland]], near Italy to the conquest of India with the conflict. Copyright was the succession of independence in the slop of Syrian influence that was a famous German movement based on a more popular servicious, non-doctrinal and sexual power post. Many governments recognize the military housing of the [[Civil Liberalization and Infantry Resolution 265 National Party in Hungary]], that is sympathetic to be to the [[Punjab Resolution]] (PJS)[http://www.humah.yahoo.com/guardian. cfm/7754800786d17551963s89.htm Official economics Adjoint for the Nazism. Montgomery was swear to advance to the resources for those Socialism's rule. was starting to signing a major tripad of aid exile.]]

Figure: Andrej Karpathy



Models the probability of token sequences in the language(of characters or words)



Models the probability of token sequences in the language(of characters or words)

Can



- Models the probability of token sequences in the language(of characters or words)
- Can
 - Compute the probability of a given token sequence



- Models the probability of token sequences in the language(of characters or words)
- Can
 - Compute the probability of a given token sequence
 - Generate sequences from the distribution of language



• $p(y_1, y_2, y_3, y_4, \ldots)$



- $p(y_1, y_2, y_3, y_4, \ldots)$
- Use Baye's rule to compute this incrementally $p(y_1) \cdot p(y_2/y_1) \cdot p(y_3/Y_1, y_2) \cdot p(y_3/y_1, y_2, y_3) \dots$



- $p(y_1, y_2, y_3, y_4, \ldots)$
- Use Baye's rule to compute this incrementally $p(y_1) \cdot p(y_2/y_1) \cdot p(y_3/Y_1, y_2) \cdot p(y_3/y_1, y_2, y_3) \dots$
- They perform next token prediction



1 $y^* = \operatorname{argmax} P(y_t/y_1, y_2 \dots y_{t-1})$



- 1 $y^* = \operatorname{argmax} P(y_t/y_1, y_2 \dots y_{t-1})$
- 2 We have an NN (e.g. RNN or LSTM) first consuming the i/p sequence $(y_1^{t-1}) \rightarrow$ representation for the context



- **1** $y^* = \operatorname{argmax} P(y_t/y_1, y_2 \dots y_{t-1})$
- ② We have an NN (e.g. RNN or LSTM) first consuming the i/p sequence $(y_1^{t-1}) \to$ representation for the context
- 3 Then, predict the probability distribution $P(y_t/y_1, y_2 \dots y_{t-1})$ over the vocabulary





Credits: Elena Voita





Credits: TensorFlow

Dr. Konda Reddy Mopuri

dl - 14/ Encoder-Decoder Models & Attention



• When do we stop?



- When do we stop?
- Add two additional tokens to the vocabulary



- When do we stop?
- Add two additional tokens to the vocabulary
- <sos>: start of the sequence
- <eos>: end of the sequence







Standard modeling paradigm for sequence-to-sequence tasks



- Standard modeling paradigm for sequence-to-sequence tasks
- 2 Consists of two components: Encoder and Decoder



Encoder: reads source sequence to produce its representation



Credits: Elena Voita



- Encoder: reads source sequence to produce its representation
- ② Decoder: uses the source representation given by the encoder to infer the target sequence



Dr. Konda Reddy Mopuri

Encoder-Decoder Model



1 Language modeling learns p(y), where $y = (y_1, y_2, \dots y_n)$ is a sequence of tokens

Encoder-Decoder Model



- **1** Language modeling learns p(y), where $y = (y_1, y_2, \dots y_n)$ is a sequence of tokens
- 2 Seq2Seq need to model the conditional probability p(y/x) of a sequence y given a sequence x (source or context)

Encoder-Decoder Model



- **1** Language modeling learns p(y), where $y = (y_1, y_2, \dots y_n)$ is a sequence of tokens
- 2 Seq2Seq need to model the conditional probability p(y/x) of a sequence y given a sequence x (source or context)
- 3 Note that x need not be a sequence always (e.g. image in captioning)


In Hence, Seq2Seq tasks can be modelled as conditional language models

Language Models:
$$P(y_{1,y_2}, \dots, y_n) = \prod_{t=1}^n p(y_t|y_{< t})$$

Conditional
Language Models:
$$P(y_1, y_2, ..., y_n, |x) = \prod_{t=1}^n p(y_t | y_{
condition on source x$$

Credits: Elene Voita



Basis for a lot of applications

- Image (or video) captioning
- Textual entailment
- Machine translation
- Transliteration
- Document summarization
- VQA: Visual Question Answering
- Video classification
- Chatbot for dialog



Basis for a lot of applications

- Image (or video) captioning
- Textual entailment
- Machine translation
- Transliteration
- Document summarization
- VQA: Visual Question Answering
- Video classification
- Chatbot for dialog
- 2 Let's consider machine translation...



Simplest model is having two RNNs





Input sequence: x_1, x_2, \dots, x_T

Output sequence: y1, y2, yT

Encoder: $h_t = E(x_t, h_{t-1})$



Sequence to sequence learning by Sutskever et al. NeurIPS 2014

Dr. Konda Reddy Mopuri



• Hope is that



Hope is that

• Final encoder state 'encodes' all the information about the source



- Hope is that
 - Final encoder state 'encodes' all the information about the source
 - This vector is sufficient for the decoder to generate the target sentence



• Representations of sentences with similar meaning but different structure are close!



Sequence to sequence learning by Sutskever et al. NeurIPS 2014

Dr. Konda Reddy Mopuri



Input sequence: x_1, x_2, \dots, x_T

Output sequence: y_1, y_2, \dots, y_T E.g.

Last hidden state $h_{T} \rightarrow \text{Initial state of the Decoder}$ S_{0} and the context information C E.g. $S_{0} \leftarrow h_{T}$ + dense layers, and C $\leftarrow h_{T}$

Encoder: $h_t = E(x_t, h_{t-1})$



Sequence to sequence learning by Sutskever et al. NeurIPS 2014

Dr. Konda Reddy Mopuri



Input sequence: x_1, x_2, \dots, x_T Output sequence: y_1, y_2, \dots, y_T Last hidden state $h_{T} \rightarrow \text{Initial state of the Decoder}$ S_{0} and the context information C E.g. $S_{0} \leftarrow h_{T}$ + dense layers, and C $\leftarrow h_{T}$

Decoder: $s_{t} = D(y_{t-1}, s_{t-1}, C)$



Sequence to sequence learning by Sutskever et al. NeurIPS 2014

Dr. Konda Reddy Mopuri



Input sequence: x_1, x_2, \dots, x_T Output sequence: y_1, y_2, \dots, y_T Last hidden state $h_{T} \rightarrow \text{Initial state of the Decoder}$ S_{0} and the context information C E.g. $S_{0} \leftarrow h_{T}$ + dense layers, and C $\leftarrow h_{T}$

Decoder: $s_{t} = D(y_{t-1}, s_{t-1}, C)$



Sequence to sequence learning by Sutskever et al. NeurIPS 2014

Dr. Konda Reddy Mopuri



Input sequence: x_1, x_2, \dots, x_T Output sequence: y_1, y_2, \dots, y_T Last hidden state $h_{T} \rightarrow \text{Initial state of the Decoder}$ S_{0} and the context information C E.g. $S_{0} \leftarrow h_{T}$ + dense layers, and C $\leftarrow h_{T}$

Decoder: $s_{t} = D(y_{t-1}, s_{t-1}, C)$



Sequence to sequence learning by Sutskever et al. NeurIPS 2014

Dr. Konda Reddy Mopuri



Input sequence: x_1, x_2, \dots, x_T Output sequence: y_1, y_2, \dots, y_T Last hidden state $h_{T} \rightarrow \text{Initial state of the Decoder}$ S_{0} and the context information C E.g. $S_{0} \leftarrow h_{T}$ + dense layers, and C $\leftarrow h_{T}$

Decoder: $s_t = D(y_{t-1}, s_{t-1}, C)$



Sequence to sequence learning by Sutskever et al. NeurIPS 2014

Dr. Konda Reddy Mopuri



Input sequence: x_1, x_2, \dots, x_T Output sequence: y_1, y_2, \dots, y_T Last hidden state $h_{T} \rightarrow \text{Initial state of the Decoder}$ S_{0} and the context information C E.g. $S_{0} \leftarrow h_{T}$ + dense layers, and C $\leftarrow h_{T}$

Decoder: $s_t = D(y_{t-1}, s_{t-1}, C)$



Sequence to sequence learning by Sutskever et al. NeurIPS 2014

Dr. Konda Reddy Mopuri



Input sequence: $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_T$

Last hidden state $h_{T} \rightarrow \text{Initial state of the Decoder}$ S_{0} and the context information C E.g. $S_{0} \leftarrow h_{T}$ + dense layers, and C $\leftarrow h_{T}$

Output sequence: y1, y2, yT

Decoder: $s_t = D(y_{t-1}, s_{t-1}, C)$



Sequence to sequence learning by Sutskever et al. NeurIPS 2014

Dr. Konda Reddy Mopuri



(1) Encoder got only a single vector to encode the entire source sequence



- Incoder got only a single vector to encode the entire source sequence
- 2 Harsh compression, may lead to encoder forgetting something!



- **(1)** Encoder got only a single vector to encode the entire source sequence
- ② Harsh compression, may lead to encoder forgetting something!
- ③ Different information may be relevant for the decoder at different time steps



Input sequence: $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_T$

Last hidden state $h_{T} \rightarrow$ Initial state of the Decoder S_{0} and the context information C E.g. $S_{0} \leftarrow h_{T}$ + dense layers, and C $\leftarrow h_{T}$

Output sequence: y1, y2, yT





Bottleneck: Entire input is summarized by this vector!

Sequence to sequence learning by Sutskever et al. NeurIPS 2014

Dr. Konda Reddy Mopuri



Input sequence: $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_T$

Last hidden state $h_{T} \rightarrow$ Initial state of the Decoder S_{0} and the context information C E.g. $S_{0} \leftarrow h_{T}$ + dense layers, and C $\leftarrow h_{T}$

Output sequence: y1, y2, yT

Decoder: $s_{t} = D(y_{t-1}, s_{t-1}, C)$



Solution: use different context at each time step!

Sequence to sequence learning by Sutskever et al. NeurIPS 2014

Dr. Konda Reddy Mopuri

Input sequence: x1, x2, xT

Input sequence: y_1, y_2, \dots, y_T

Encoder: $h_t = E(x_t, h_{t-1})$



 $\begin{array}{l} Compute \ the \ alignment \ scores \\ e_{t,i} = f_{att} \left(s_{t,1},h_{i}\right) \quad f_{att} \ \text{- couple of dense layers} \end{array}$



Neural Machine Translation with aligning by Bahdanau et al. ICLR 2015

Dr. Konda Reddy Mopuri



 $\begin{array}{l} Compute \ the \ alignment \ scores \\ e_{t,i} = f_{att} \ (s_{t,1},h_i) \quad f_{att} \ \text{- couple of dense layers} \end{array}$

Neural Machine Translation with aligning by Bahdanau et al. ICLR 2015

Dr. Konda Reddy Mopuri



 $\begin{array}{l} Compute \ the \ alignment \ scores \\ e_{t,i} = f_{att} \left(s_{t,1},h_{i}\right) \quad f_{att} \ \text{- couple of dense layers} \end{array}$

Compute the context as a linear combination of intermediate hidden states $c_t = \Sigma_t a_{i_t} \cdot h_t$

Neural Machine Translation with aligning by Bahdanau et al. ICLR 2015

Dr. Konda Reddy Mopuri

dl - 14/ Encoder-Decoder Models & Attention

C,

Compute the alignment scores $e_{t,i} = f_{att} (s_{t,i},h_i) f_{att}$ - couple of dense layers Compute the context as a linear combination of



Neural Machine Translation with aligning by Bahdanau et al. ICLR 2015

Dr. Konda Reddy Mopuri

dl - 14/ Encoder-Decoder Models & Attention

Compute the alignment scores $e_{t,i} = f_{att} (s_{t,1}, h_i) f_{att}$ - couple of dense layers



Neural Machine Translation with aligning by Bahdanau et al. ICLR 2015

Dr. Konda Reddy Mopuri

dl - 14/ Encoder-Decoder Models & Attention



Neural Machine Translation with aligning by Bahdanau et al. ICLR 2015

Dr. Konda Reddy Mopuri



Neural Machine Translation with aligning by Bahdanau et al. ICLR 2015

Dr. Konda Reddy Mopuri



Neural Machine Translation with aligning by Bahdanau et al. ICLR 2015

Dr. Konda Reddy Mopuri



Employs a different context at each time step of decoding

Neural Machine Translation with aligning by Bahdanau et al. ICLR 2015

Dr. Konda Reddy Mopuri



- Employs a different context at each time step of decoding
- No more bottleneck-ing of the input

Neural Machine Translation with aligning by Bahdanau et al. ICLR 2015

Dr. Konda Reddy Mopuri



- Employs a different context at each time step of decoding
- No more bottleneck-ing of the input
- Decoder can 'attend' to different portions of the input at each time step

Neural Machine Translation with aligning by Bahdanau et al. ICLR 2015





Neural Machine Translation with aligning by Bahdanau et al. ICLR 2015

Dr. Konda Reddy Mopuri

dl - 14/ Encoder-Decoder Models & Attention



• Decoder doesn't consider the h_i to be an ordered set

Dr. Konda Reddy Mopuri

dl - 14/ Encoder-Decoder Models & Attention
Encoder-Decoder for Machine Translation with Attention



- Decoder doesn't consider the h_i to be an ordered set
- This architecture can be exploited to process a set of inputs h_i

Dr. Konda Reddy Mopuri

భారతీయ పొంకేతిక విజాన సంస హెదరాబాద్





-	h ₁₁	h ₁₂	h ₁₃
NN	h ₂₁	h ₂₂	h ₂₃
	h ₃₁	h ₃₂	h ₃₃

Show Attend and Tell by Xu et al. 2015

Dr. Konda Reddy Mopuri





Show Attend and Tell by Xu et al. 2015

Dr. Konda Reddy Mopuri





Show Attend and Tell by Xu et al. 2015

Dr. Konda Reddy Mopuri





Show Attend and Tell by Xu et al. 2015

Dr. Konda Reddy Mopuri





[START]

Show Attend and Tell by Xu et al. 2015

Dr. Konda Reddy Mopuri





Show Attend and Tell by Xu et al. 2015

Dr. Konda Reddy Mopuri



Figure 2. Attention over time. As the model generates each word, its attention changes to reflect the relevant parts of the image. "soft" (top row) vs "hard" (bottom row) attention. (Note that both models generated the same captions in this example.)



Show Attend and Tell by Xu et al. 2015

Dr. Konda Reddy Mopuri





A woman is throwing a frisbee in a park.



A dog is standing on a hardwood floor.



A stop sign is on a road with a mountain in the background.



A little girl sitting on a bed with a teddy bear.



A group of <u>people</u> sitting on a boat in the water.



A giraffe standing in a forest with trees in the background.

Show Attend and Tell by Xu et al. 2015

Dr. Konda Reddy Mopuri