

Deep Learning

5 Backpropagation-1

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Recap



- Gradient of a scalar valued function $f(\mathbf{x}): \mathbf{x} \rightarrow \left(\frac{\partial f}{\partial x_1}, \dots, \frac{\partial f}{\partial x_D} \right)^T$

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- Gradient of a scalar valued function $f(\mathbf{x})$: $\mathbf{x} \rightarrow \left(\frac{\partial f}{\partial x_1}, \dots, \frac{\partial f}{\partial x_D} \right)^T$
- Gradient of a vector valued function $\mathbf{f}(\mathbf{x})$ is called Jacobian:

$$\mathbf{J} = \begin{bmatrix} \frac{\partial \mathbf{f}}{\partial x_1} & \dots & \frac{\partial \mathbf{f}}{\partial x_n} \end{bmatrix} = \begin{bmatrix} \nabla^T f_1 \\ \vdots \\ \nabla^T f_m \end{bmatrix} = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \dots & \frac{\partial f_1}{\partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_m}{\partial x_1} & \dots & \frac{\partial f_m}{\partial x_n} \end{bmatrix}$$

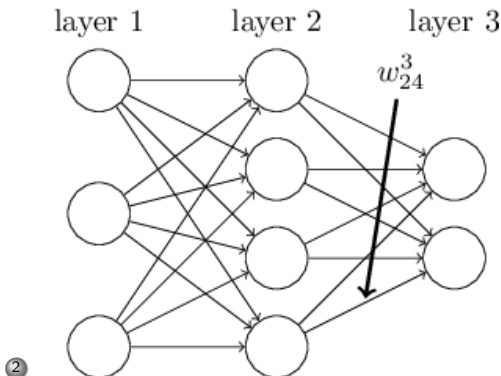
MLP: Some Notation



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$$x_j^l = \sigma\left(\sum_k w_{jk}^l x_k^{l-1} + b_j^l\right)$$

- ④ Vector of activations (or, biases) at a layer l is denoted by a bold-faced \mathbf{x}^l (or \mathbf{b}^l) and W^l is the matrix of weights into layer l

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- ④ σ is the activation function that applies element-wise

Gradient descent on MLP



- Loss is $\mathcal{L}(W, \mathbf{b}) = \sum_n l(f(x_n; W, \mathbf{b}), y_n) = \sum_n l(\mathbf{x}^L, y_n)$ (L is the number of layers in the MLP)

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- For applying Gradient descent, we need gradient of individual sample loss with respect to all the model parameters

$$l_n = l(f(x_n; W, \mathbf{b}), y_n)$$

$$\frac{\partial l_n}{\partial W_{jk}^{(l)}} \text{ and } \frac{\partial l_n}{\partial \mathbf{b}_j^{(l)}} \text{ for all layers } l$$

Forward pass operation



$$x^{(0)} = x \xrightarrow{W^{(1)}, \mathbf{b}^{(1)}} s^{(1)} \xrightarrow{\sigma} x^{(1)} \xrightarrow{W^{(2)}, \mathbf{b}^{(2)}} s^{(2)} \dots x^{(L-1)} \xrightarrow{W^{(L)}, \mathbf{b}^{(L)}} s^{(L)} \xrightarrow{\sigma} x^{(L)} = f(x; W, \mathbf{b})$$

Formally, $x^{(0)} = x, f(x; W, \mathbf{b}) = x^{(L)}$

$$\forall l = 1, \dots, L \quad \begin{cases} s^{(l)} & = W^{(l)}x^{(l-1)} + \mathbf{b}^{(l)} \\ x^{(l)} & = \sigma(s^{(l)}) \end{cases}$$

Chain rule of differential calculus



- Core concept of backpropagation

Chain rule of differential calculus



- Core concept of backpropagation



$$(g \circ f)'(x) = g'(f(x)) \cdot f'(x)$$

Chain rule of differential calculus

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$$\frac{\partial}{\partial x} g(f(x)) = \frac{\partial g(a)}{\partial a} \Big|_{a=f(x)} \cdot \frac{\partial f(x)}{\partial x}$$

Chain rule of differential calculus

 The Chain Rule

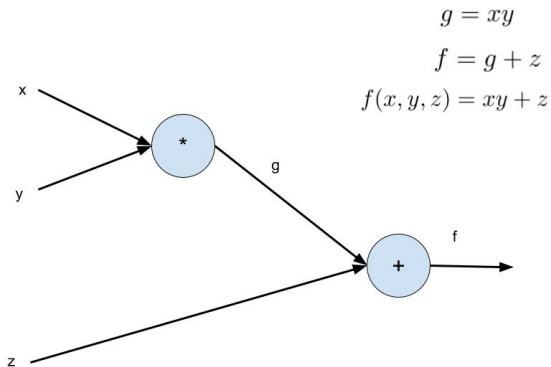
$$\frac{dy}{dx} = \frac{dy}{du} \cdot \frac{du}{dx}$$
$$\frac{dy}{dx} = \left(\begin{array}{l} \text{Differentiate} \\ \text{outer function} \\ \text{Keep the inside} \\ \text{the same} \end{array} \right) \left(\begin{array}{l} \text{Differentiate} \\ \text{inner function} \end{array} \right)$$

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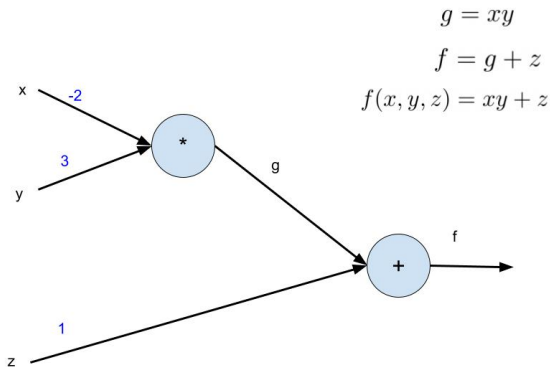
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① $f(x) = e^{\sin(x^2)}$, let's find $\frac{\partial f}{\partial x}$ (work it out on the board)

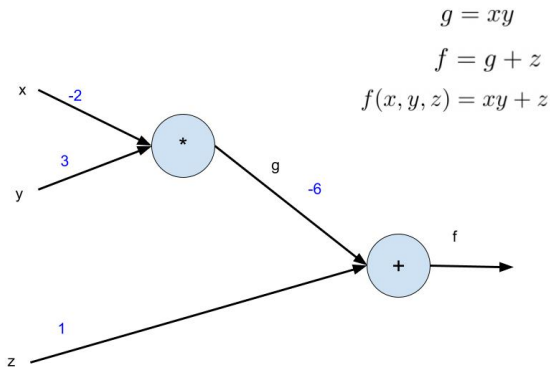
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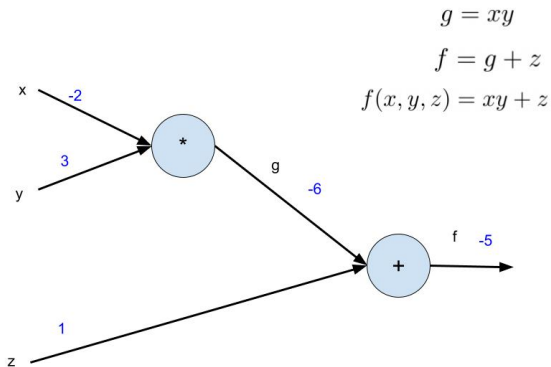
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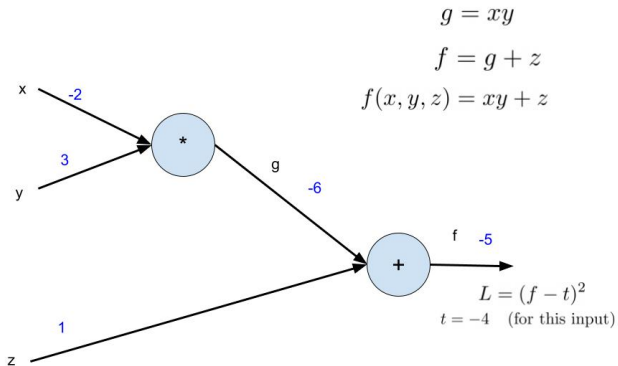
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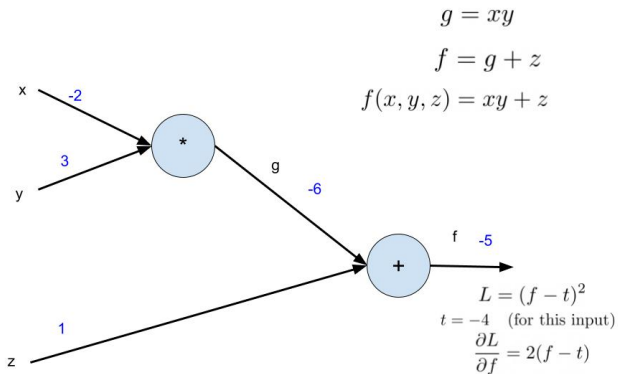
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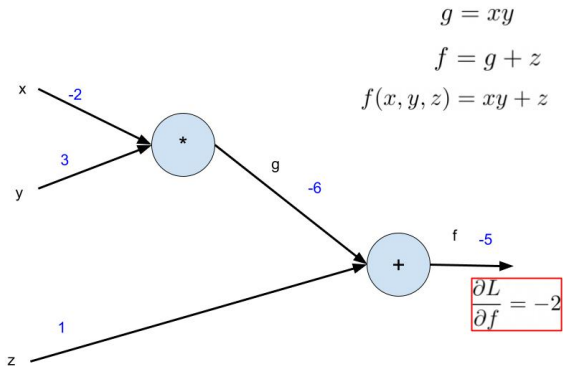
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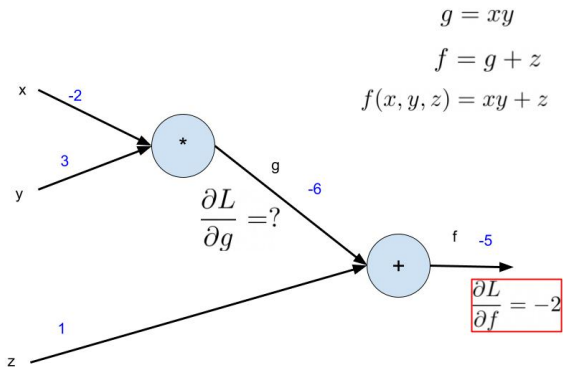
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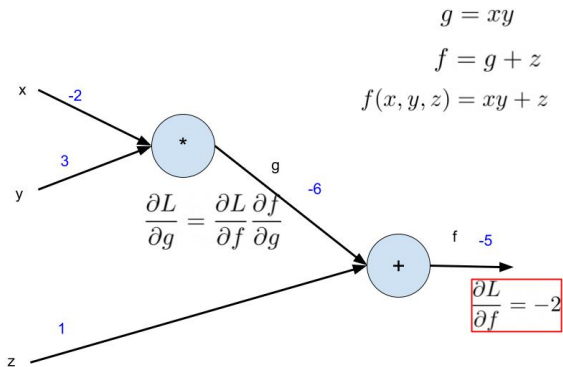
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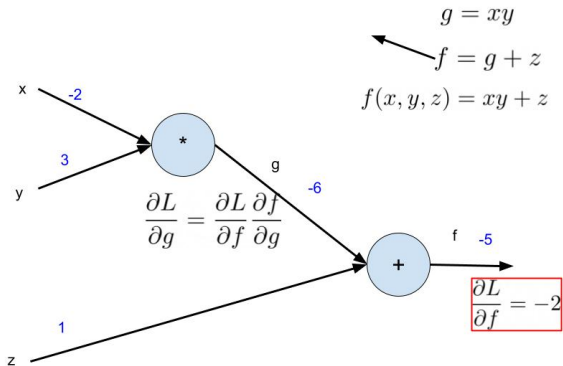
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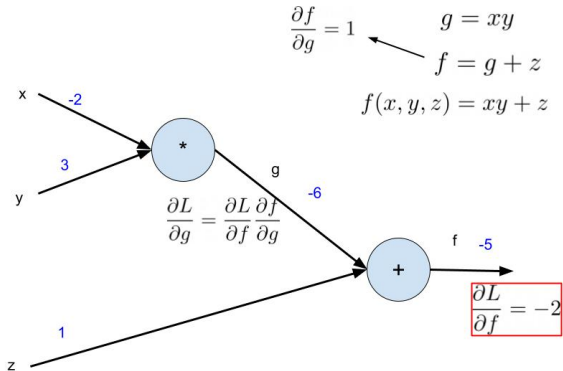
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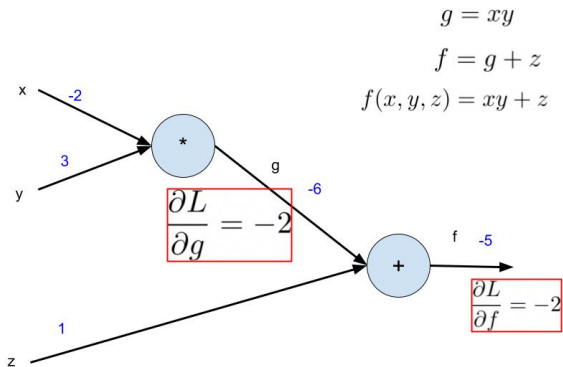
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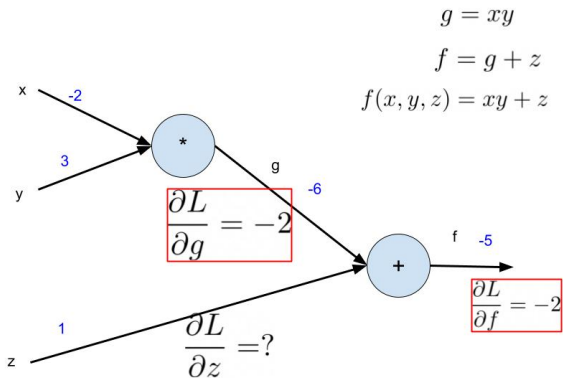
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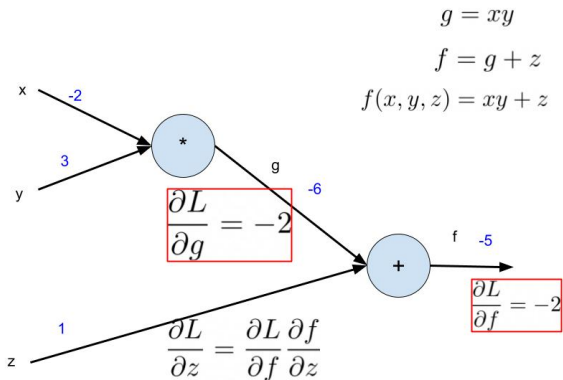
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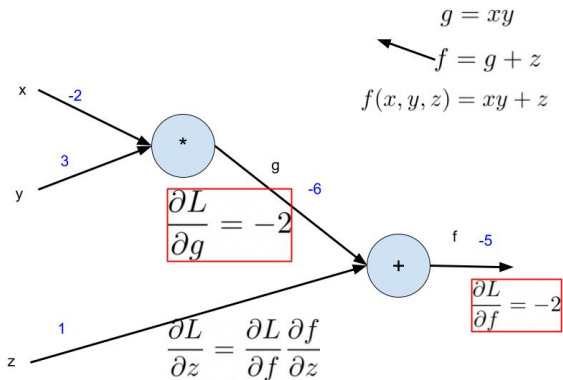
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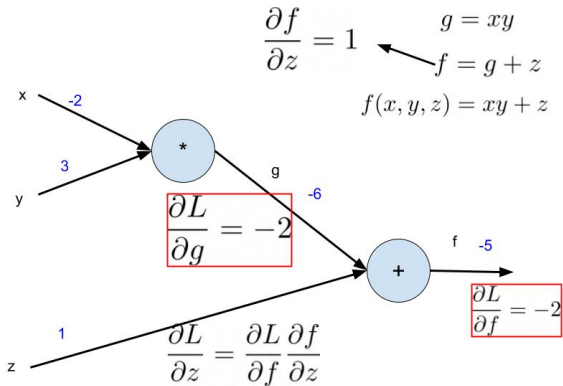
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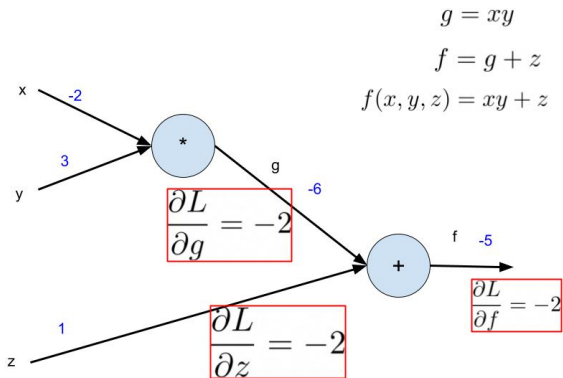
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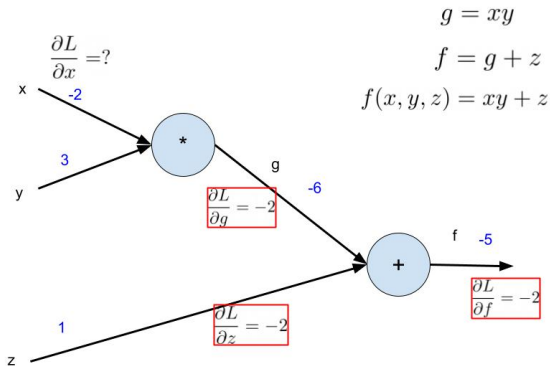
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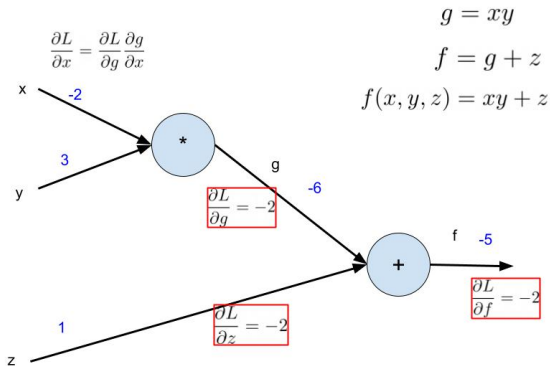
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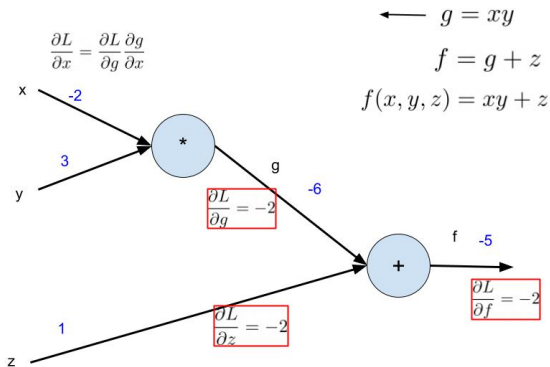
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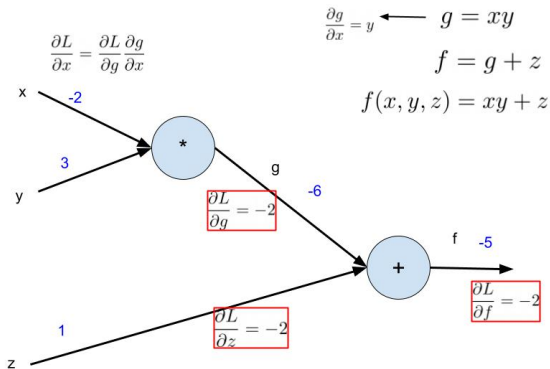
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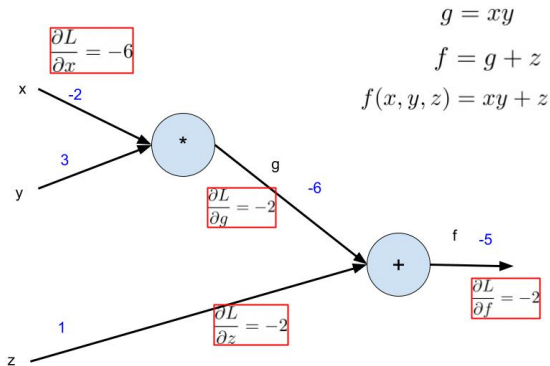
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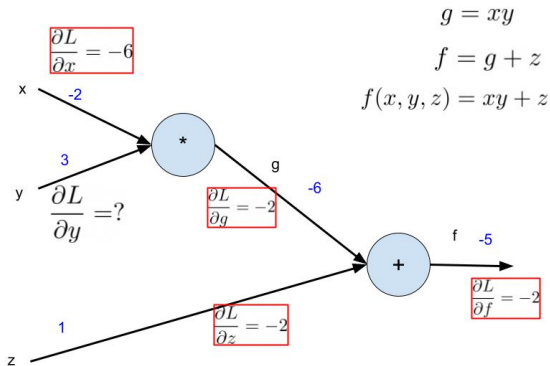
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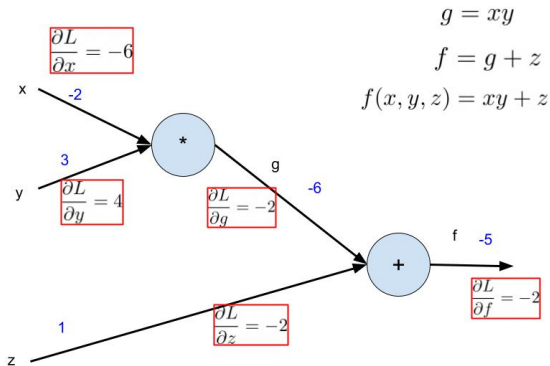
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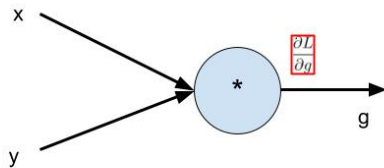
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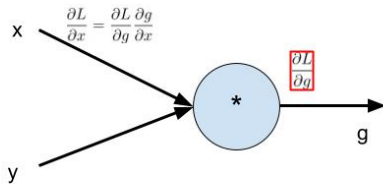
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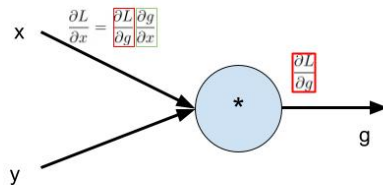
Gradient Flow



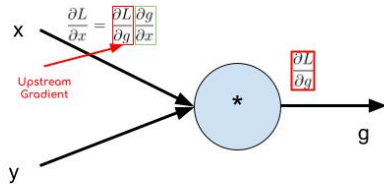
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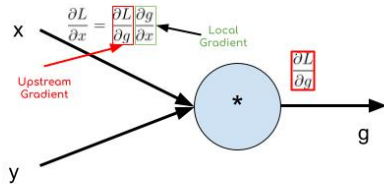
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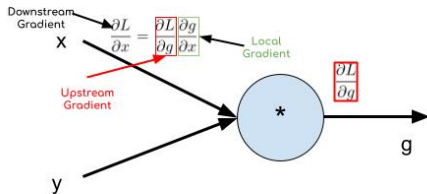
Gradient Flow



Gradient Flow



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Chain rule of differential calculus for an MLP



$$J_{f_N \circ f_{N-1} \circ \dots \circ f_1(x)} = J_{f_N}(f_{N-1}(\dots f_1(x))) \cdot J_{f_{N-1}}(f_{N-2}(\dots f_1(x))) \cdot \dots \cdot J_{f_2}(f_1(x)) \cdot J_{f_1}(x)$$

$J_{f(x)}$ is Jacobian of f computed at x .