

# **Deep Learning**

### 15 Encoder-Decoder Models & Attention

Dr. Konda Reddy Mopuri Dept. of Al, IIT Hyderabad Jan-May 2023



1  $y^* = \operatorname{argmax} P(y_t/y_1, y_2 \dots y_{t-1})$ 

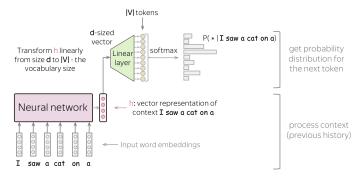


- 1  $y^* = \operatorname{argmax} P(y_t/y_1, y_2 \dots y_{t-1})$
- 2 We have an NN (e.g. RNN or LSTM) first consuming the i/p sequence  $(y_1^{t-1}) \rightarrow$  representation for the context



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- 2 We have an NN (e.g. RNN or LSTM) first consuming the i/p sequence  $(y_1^{t-1}) \to$  representation for the context
- 3 Then, predict the probability distribution  $P(y_t/y_1, y_2 \dots y_{t-1})$  over the vocabulary





Credits: Elena Voita



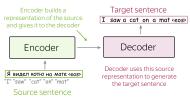
Standard modeling paradigm for sequence-to-sequence tasks



- Standard modeling paradigm for sequence-to-sequence tasks
- 2 Consists of two components: Encoder and Decoder



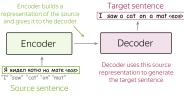
Encoder: reads source sequence to produce its representation



Credits: Elena Voita



- Encoder: reads source sequence to produce its representation
- ② Decoder: uses the source representation given by the encoder to infer the target sequence



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- 2 Seq2Seq need to model the conditional probability p(y/x) of a sequence y given a sequence x (source or context)
- 3 Note that x need not be a sequence always (e.g. image in captioning)



In Hence, Seq2Seq tasks can be modelled as conditional language models

Language Models: 
$$P(y_1, y_2, \dots, y_n) = \prod_{t=1}^n p(y_t | y_{< t})$$

Conditional  
Language Models: 
$$P(y_1, y_2, ..., y_n, |x) = \prod_{t=1}^n p(y_t | y_{  
condition on source x$$

Credits: Elene Voita



Basis for a lot of applications

- Image (or video) captioning
- Textual entailment
- Machine translation
- Transliteration
- Document summarization
- VQA: Visual Question Answering
- Video classification
- Chatbot for dialog

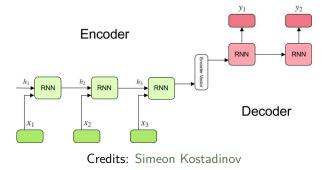


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- 2 Let's consider machine translation...



Simplest model is having two RNNs





Input sequence:  $x_1, x_2, \dots, x_T$ 

Output sequence: y1, y2, .... yT

Encoder:  $h_t = E(x_t, h_{t-1})$ 



Sequence to sequence learning by Sutskever et al. NeurIPS 2014

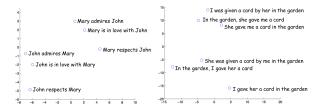
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- Hope is that
  - final encoder state 'encodes' all the information about the source
  - this vector is sufficient for the decoder to generate the target sentence



• Representations of sentences with similar meaning but different structure are close!



Sequence to sequence learning by Sutskever et al. NeurIPS 2014

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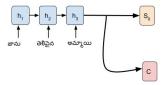


Input sequence:  $x_1, x_2, \dots, x_T$ 

Output sequence: y<sub>1</sub>, y<sub>2</sub>, ..., y<sub>T</sub> E.g.

Last hidden state  $h_{T} \rightarrow \text{Initial state of the Decoder}$  $S_{0}$  and the context information C E.g.  $S_{0} \leftarrow h_{T}$  + dense layers, and C  $\leftarrow h_{T}$ 

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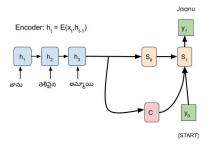
Sequence to sequence learning by Sutskever et al. NeurIPS 2014

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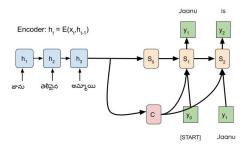
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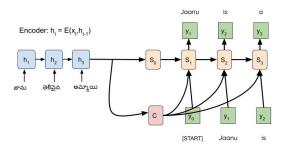
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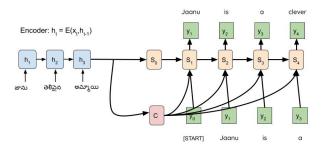
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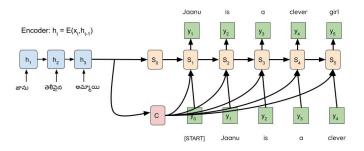
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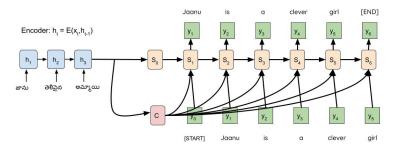


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(1) Encoder got only a single vector to encode the entire source sequence



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- 2 Harsh compression, may lead to encoder forgetting something!



- **(1)** Encoder got only a single vector to encode the entire source sequence
- ② Harsh compression, may lead to encoder forgetting something!
- ③ Different information may be relevant for the decoder at different time steps

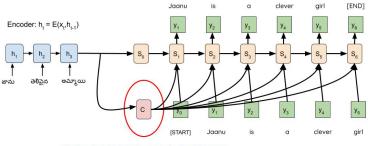


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Bottleneck: Entire input is summarized by this vector!

#### Sequence to sequence learning by Sutskever et al. NeurIPS 2014

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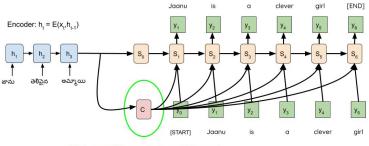


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Solution: use different context at each time step!

#### Sequence to sequence learning by Sutskever et al. NeurIPS 2014

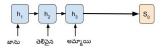
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## Encoder-Decoder for Machine Translation with Attention

Input sequence: x1, x2, .... xT

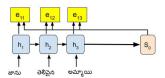
Input sequence:  $y_1, y_2, \dots, y_T$ 

Encoder:  $h_t = E(x_t, h_{t-1})$ 



## Encoder-Decoder for Machine Translation with Attention of the action of

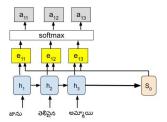
 $\begin{array}{l} Compute \ the \ alignment \ scores \\ e_{t,i} = f_{att} \ (s_{t,1},h_i) \quad f_{att} \ \text{- couple of dense layers} \end{array}$ 



#### Neural Machine Translation with aligning by Bahdanau et al. ICLR 2015

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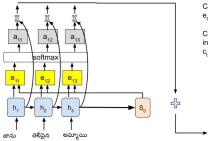


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### Encoder-Decoder for Machine Translation with Attention



 $\begin{array}{l} Compute \ the \ alignment \ scores \\ e_{t,i} = f_{att} \left(s_{t,1},h_{i}\right) \quad f_{att} \ \text{- couple of dense layers} \end{array}$ 

Compute the context as a linear combination of intermediate hidden states  $c_t = \Sigma_t a_{i_t} \cdot h_t$ 

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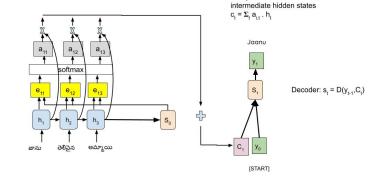
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భారతీయ పొంకేతిక విజ్ఞాన సంస్థ హైదరాబాద్

### Encoder-Decoder for Machine Translation with Attention

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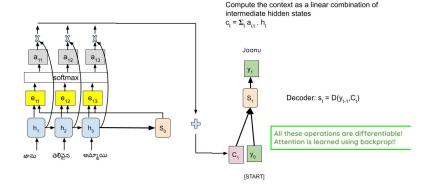
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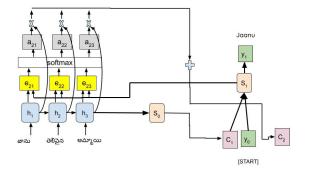


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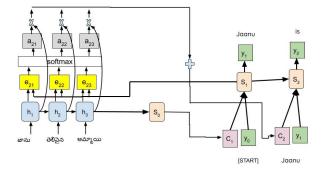
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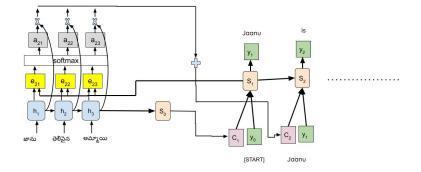
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Employs a different context at each time step of decoding

Neural Machine Translation with aligning by Bahdanau et al. ICLR 2015

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- Employs a different context at each time step of decoding
- No more bottleneck-ing of the input

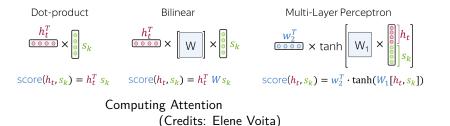
Neural Machine Translation with aligning by Bahdanau et al. ICLR 2015

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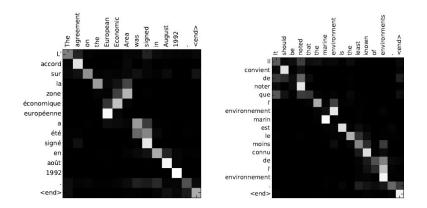


- Employs a different context at each time step of decoding
- No more bottleneck-ing of the input
- Decoder can 'attend' to different portions of the input at each time step

## Neural Machine Translation with aligning by Bahdanau et al. ICLR 2015



భారతీయ పాంకేతిక విజాన సంస హైదరాబాద్

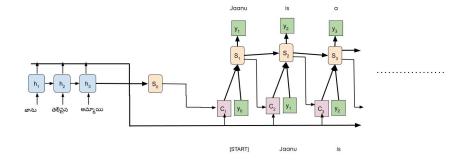


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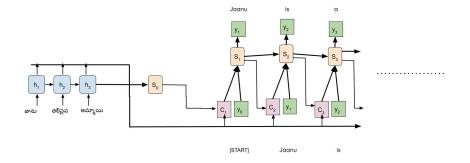


## • Decoder doesn't consider the $h_i$ to be an ordered set

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భారతీయ పొంకేతిక విజాన సంస హెదరాబాద్



- Decoder doesn't consider the  $h_i$  to be an ordered set
- This architecture can be exploited to process a set of inputs  $h_i$

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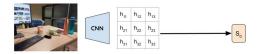


_	h <sub>11</sub>	h <sub>12</sub>	h <sub>13</sub>
NN	h <sub>21</sub>	h <sub>22</sub>	h <sub>23</sub>
_	h <sub>31</sub>	h <sub>32</sub>	h <sub>33</sub>

### Show Attend and Tell by Xu et al. 2015

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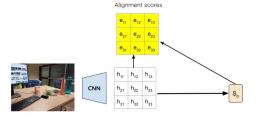




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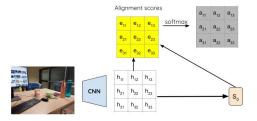




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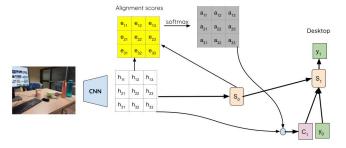




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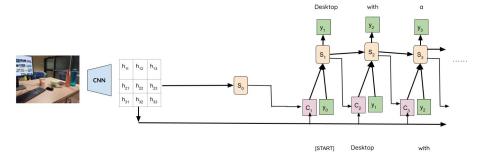


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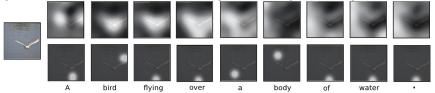


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Figure 2. Attention over time. As the model generates each word, its attention changes to reflect the relevant parts of the image. "soft" (top row) vs "hard" (bottom row) attention. (Note that both models generated the same captions in this example.)



Show Attend and Tell by Xu et al. 2015

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A woman is throwing a frisbee in a park.



A dog is standing on a hardwood floor.



A stop sign is on a road with a mountain in the background.



A little girl sitting on a bed with a teddy bear.



A group of <u>people</u> sitting on a boat in the water.



A giraffe standing in a forest with trees in the background.

### Show Attend and Tell by Xu et al. 2015

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